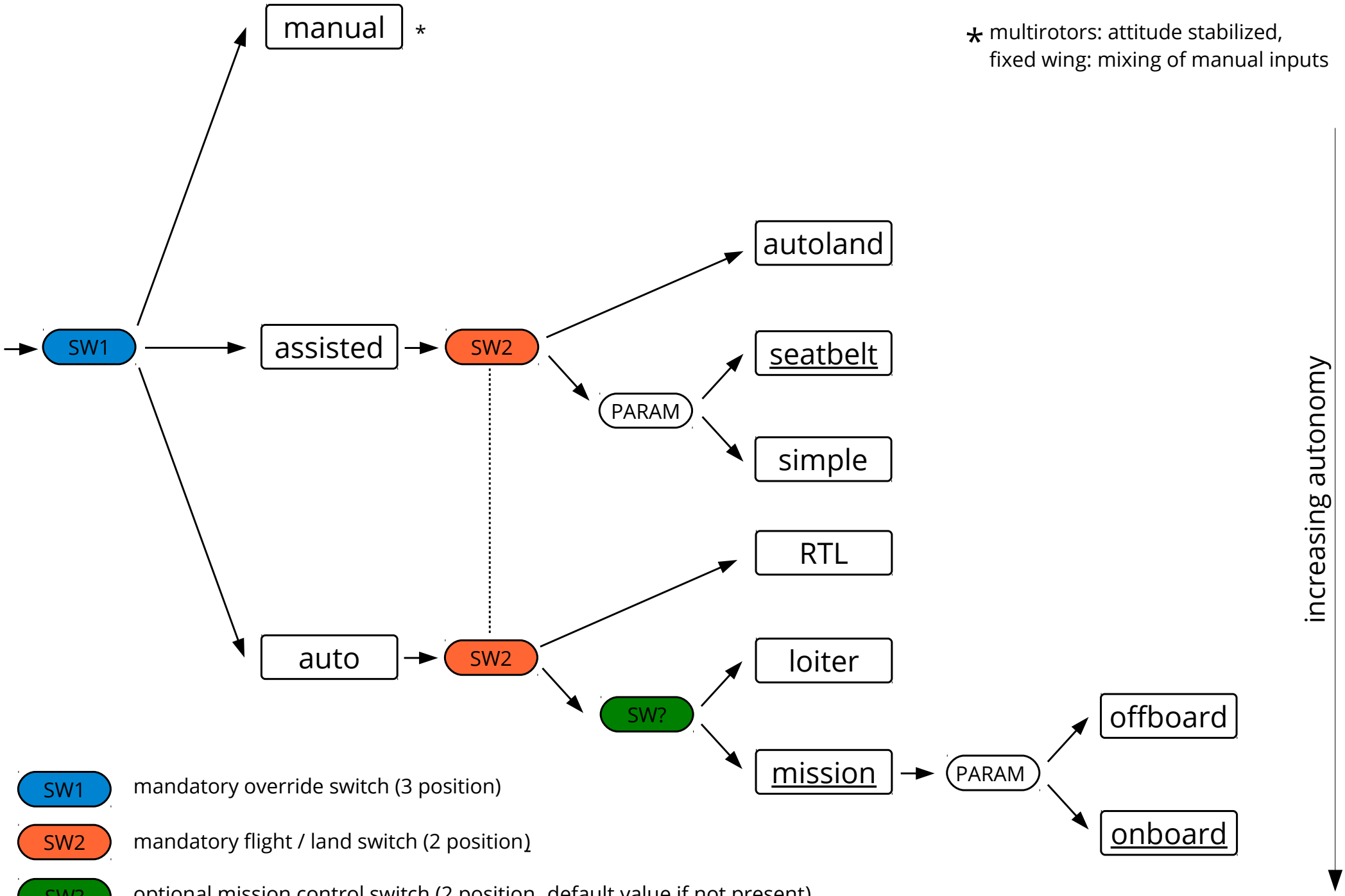
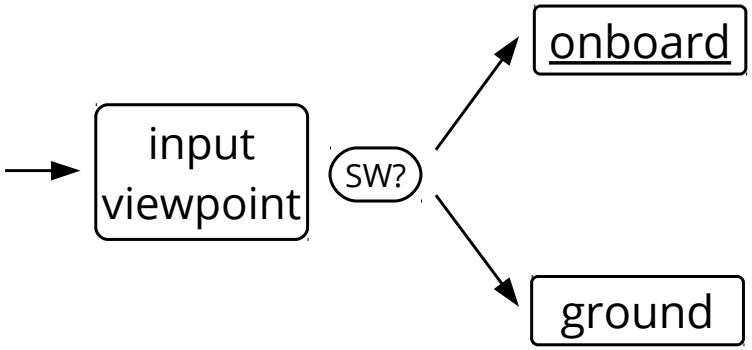


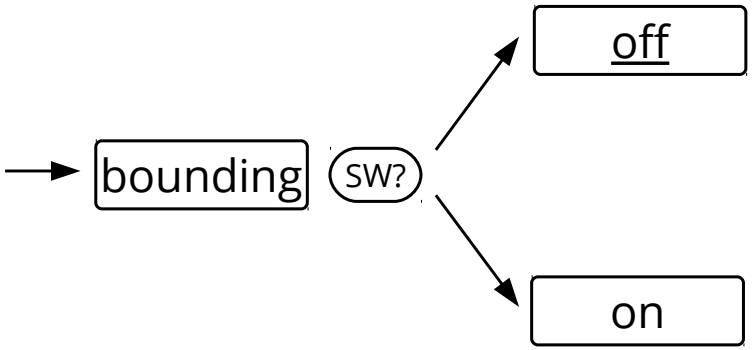
SW1 mandatory override switch (3 position)

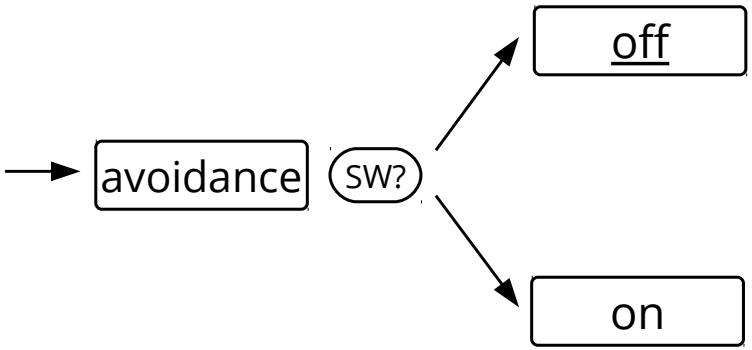
SW2 mandatory flight / land switch (2 position)

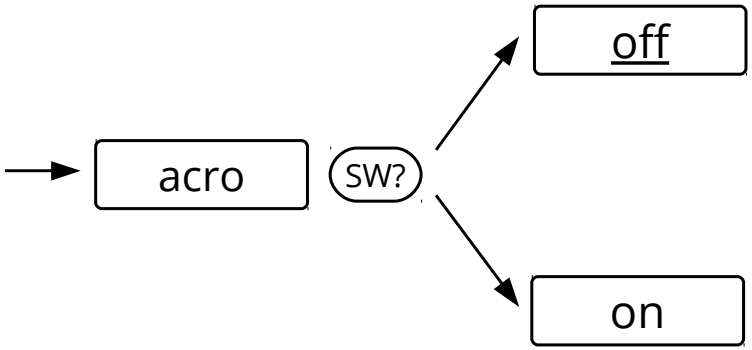
SW? optional mission control switch (2 position, default value if not present)

PARAM mode depends on parameter (default value is underlined)


input viewpoint
SW?
onboard
ground


bounding
SW?
off
on


avoidance
SW?
off
on


acro
SW?
off
on